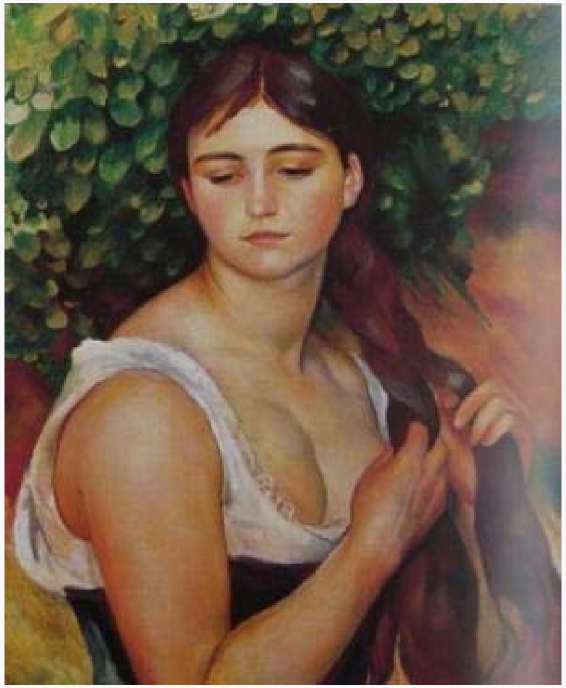
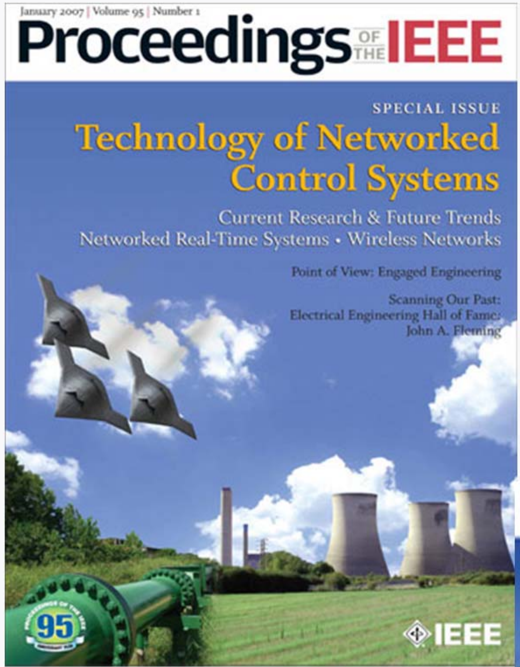
The Complex Braid of Communication and Control



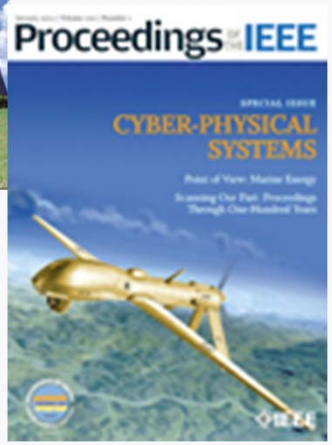
Massimo Franceschetti

UCSD

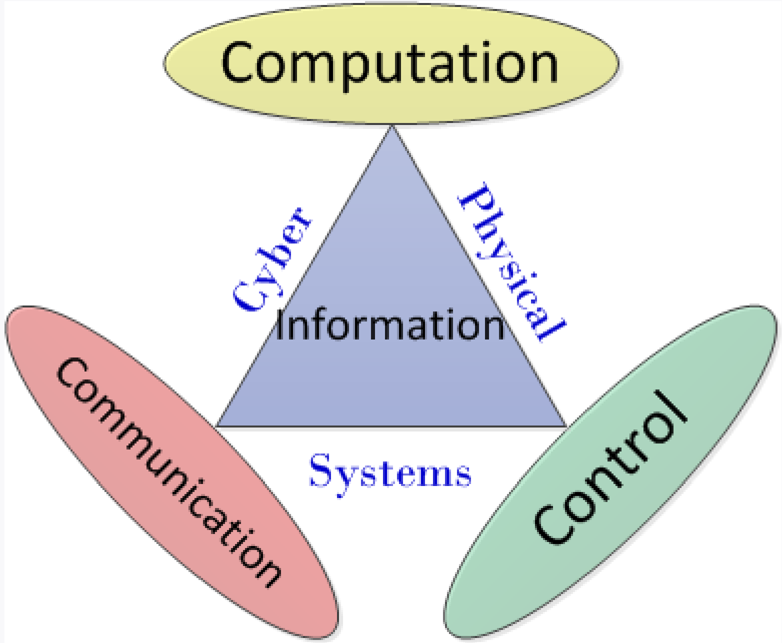
Motivation



January 2007

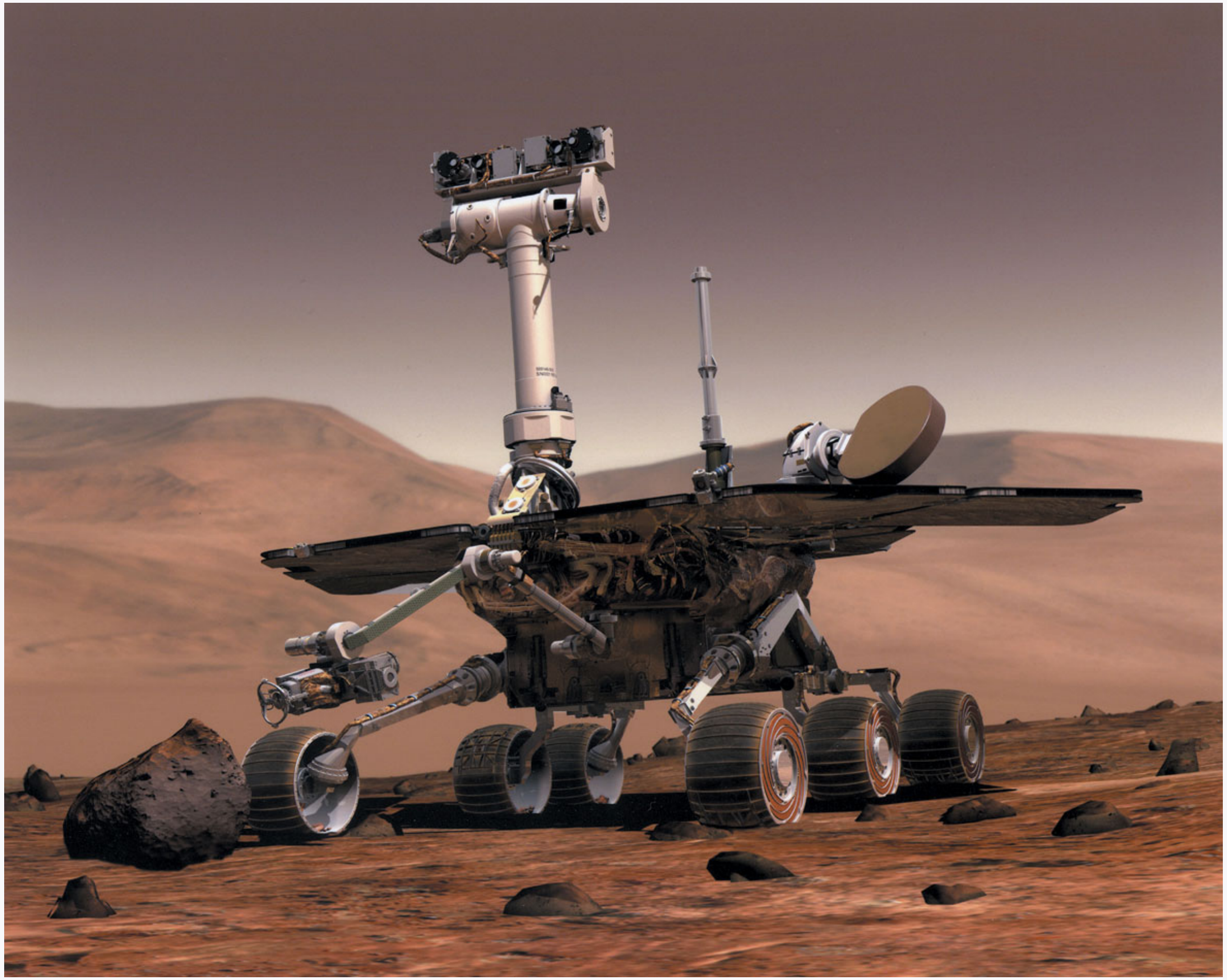


January 2012

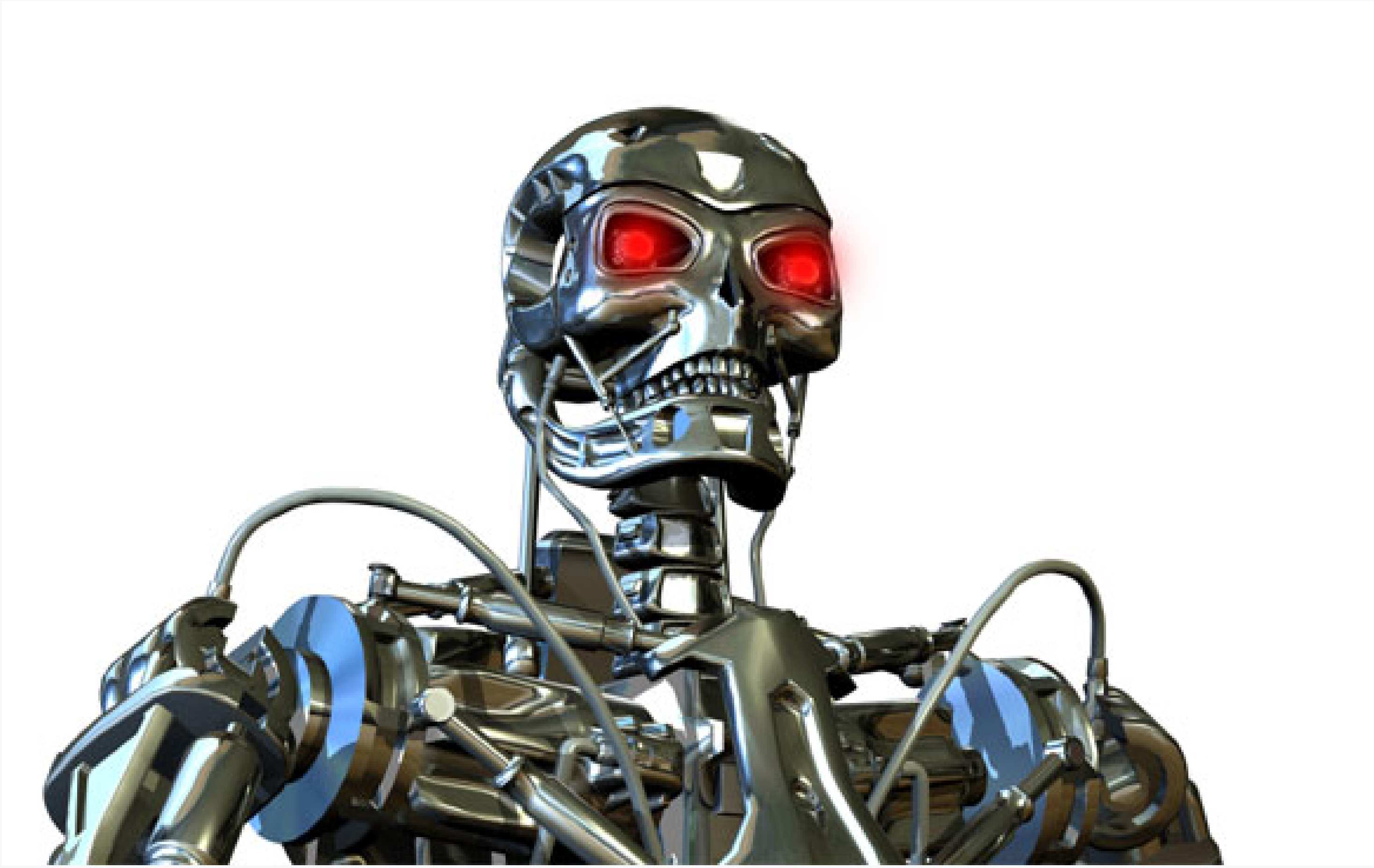


Motivation

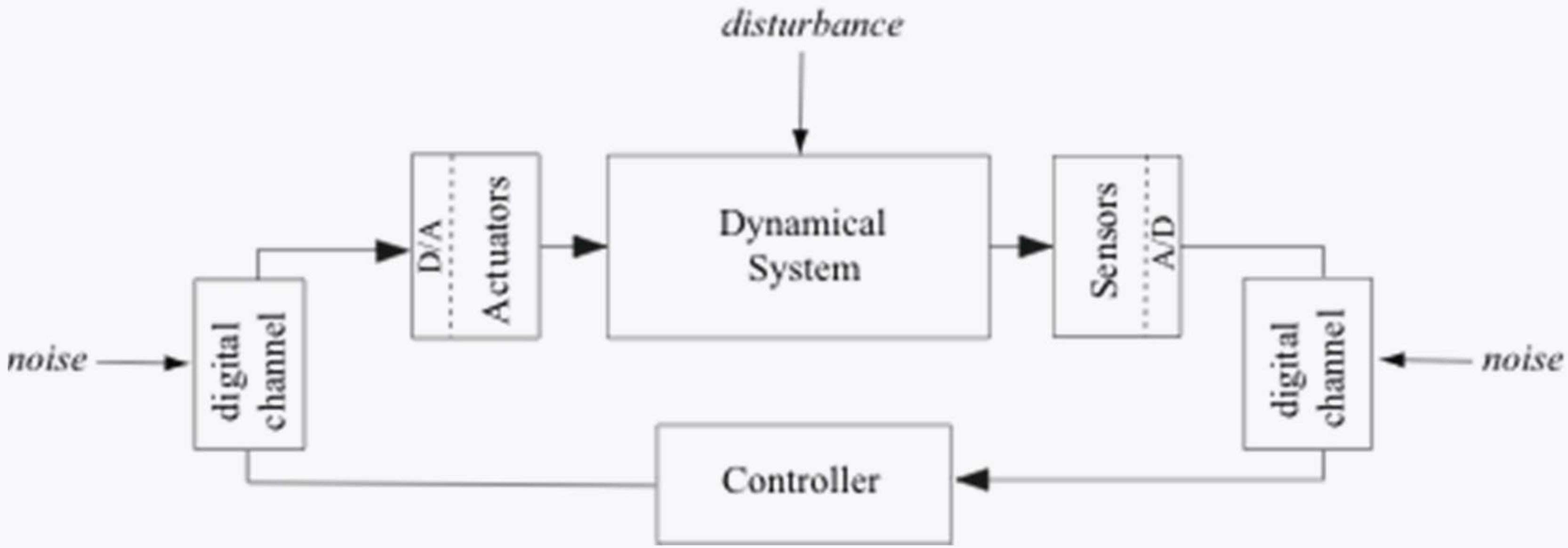
Motivation

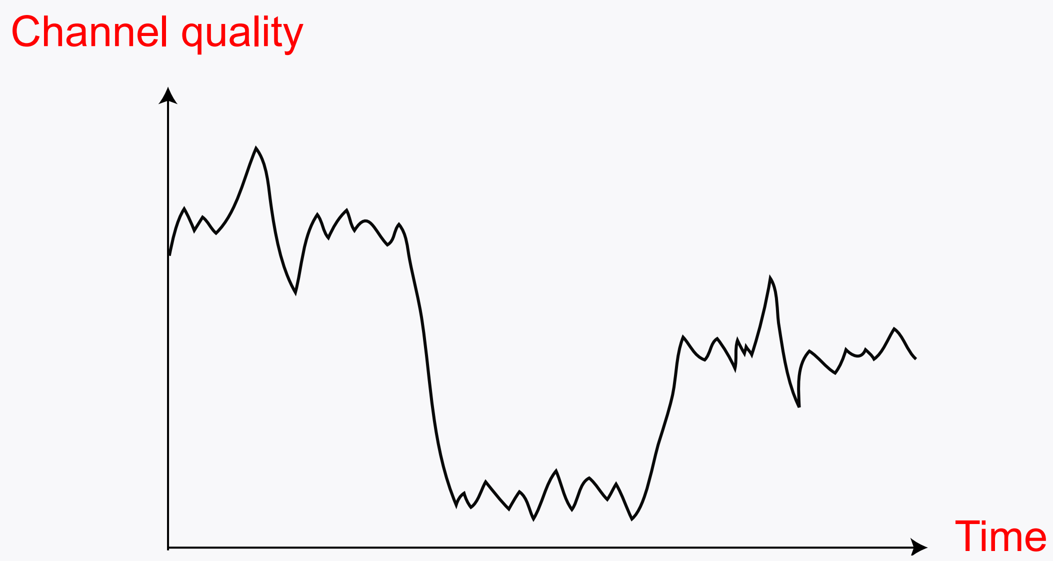


Motivation



Abstraction





Problem formulation

- Linear dynamical system

$$\begin{aligned} x_{k+1} &= Ax_k + Bu_k + v_k, \\ y_k &= Cx_k + w_k \end{aligned}$$

A composed of unstable modes $|\lambda_1| \geq 1, \cdots, |\lambda_n| \geq 1$

- Time-varying channel

Slotted time-varying channel evolving at the same time scale of the system

Problem formulation

Objective: identify the trade-off between system's unstable modes and channel's rate to guarantee stability:

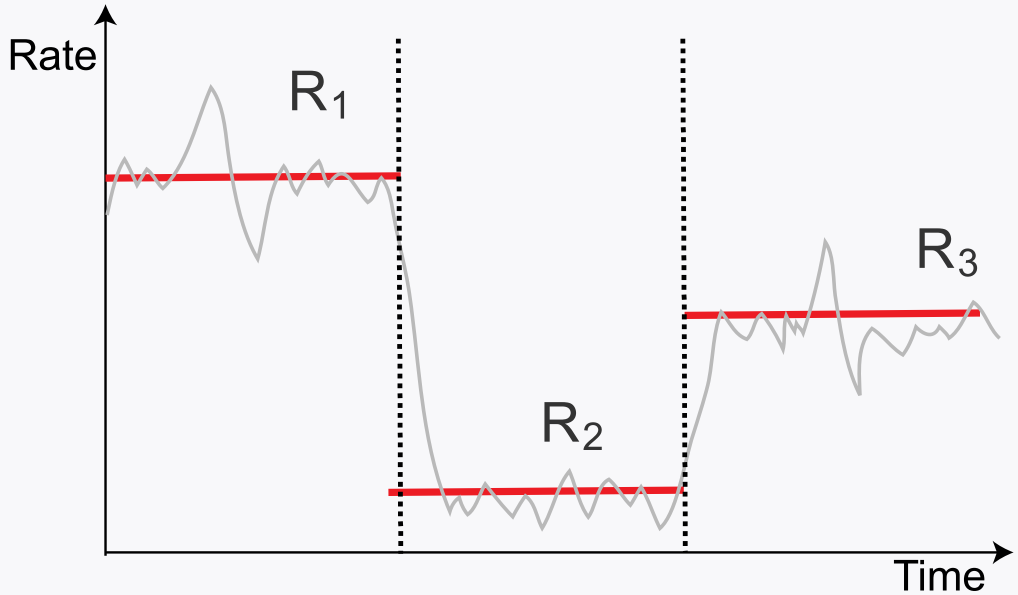
$$\sup_k ||x_k|| < \infty$$

or

$$\sup_k \mathbb{E}[||x_k||^2] < \infty$$

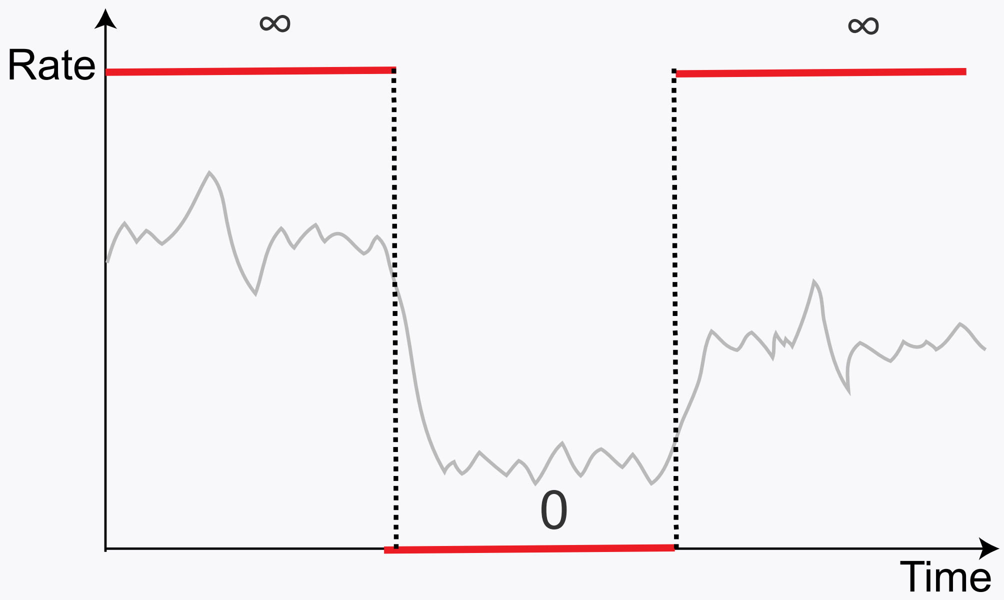
Information-theoretic approach

- A **rate-based** approach, transmit R_k bits/time
- Derive **data-rate theorems** quantifying how much rate is needed to construct a stabilizing quantizer/controller pair



Network-theoretic approach

- A **packet-based** approach (a packet models a real number)
- Determine the **critical packet loss probability** above which the system cannot be stabilized by any control scheme



Information-theoretic approach

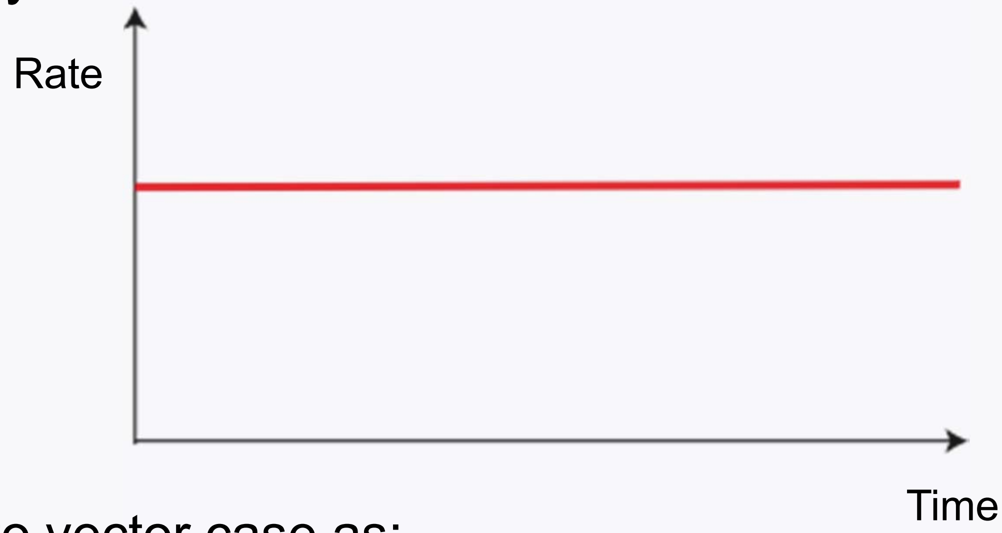
- Tatikonda-Mitter (IEEE-TAC 2002)

  Rate process $\forall k \;\; R_k = R$ known at the transmitter

  Disturbances and initial state support: bounded

  Data rate theorem: $R > R_c = \log|\lambda|$

  a.s. stability



- Generalizes to vector case as:

$$R > \sum_u m_u \log|\lambda_u|$$

Information-theoretic approach

- Nair-Evans (SIAM-JCO 2004)

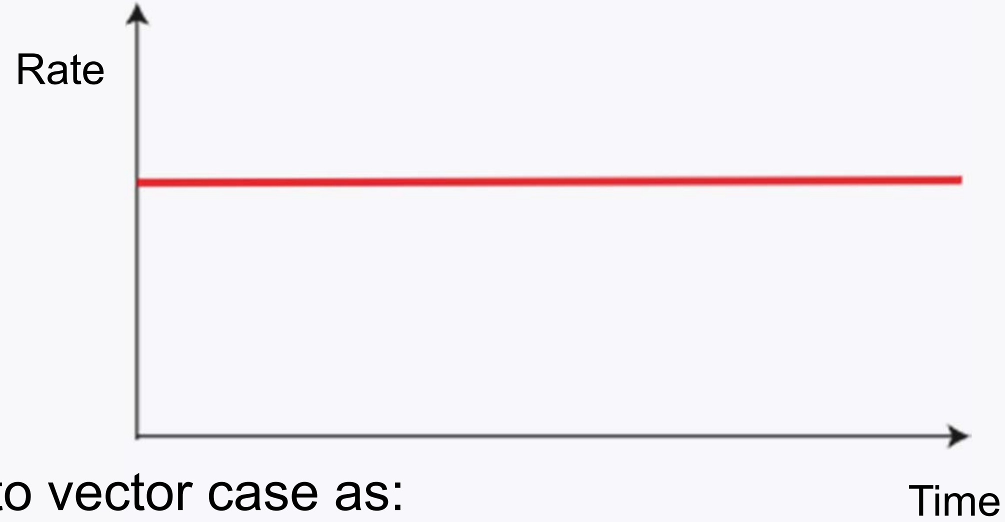
  Rate process: $\forall k \; R_k = R$ known at the transmitter

  Disturbances and initial state support: unbounded

  Bounded higher moment (e.g. Gaussian distribution)

  Data rate theorem: $R > R_c = \log|\lambda|$

  Second moment stability



- Generalizes to vector case as:

$$R > \sum_u m_u \log|\lambda_u|$$

Intuition

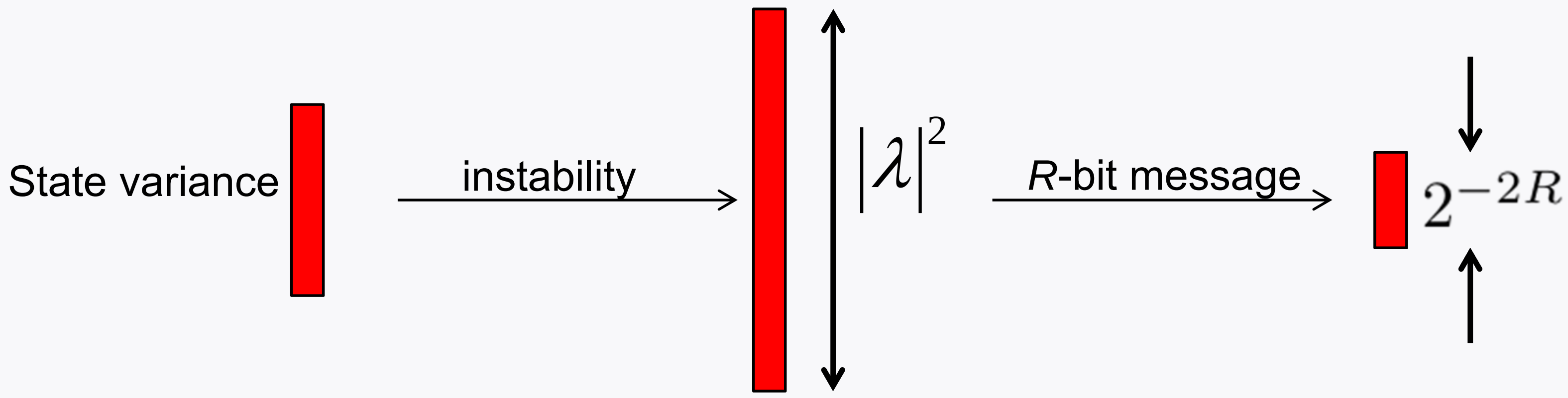
- Want to compensate for the expansion of the state during the communication process

- At each time step, the uncertainty volume of the state

$$\uparrow |\lambda|^2 \qquad \downarrow 2^{-2R}$$

- Keep the product less than one for second moment stability

$$R > \log|\lambda|$$



Information-theoretic approach

- Martins-Dahleh-Elia (IEEE-TAC 2006)

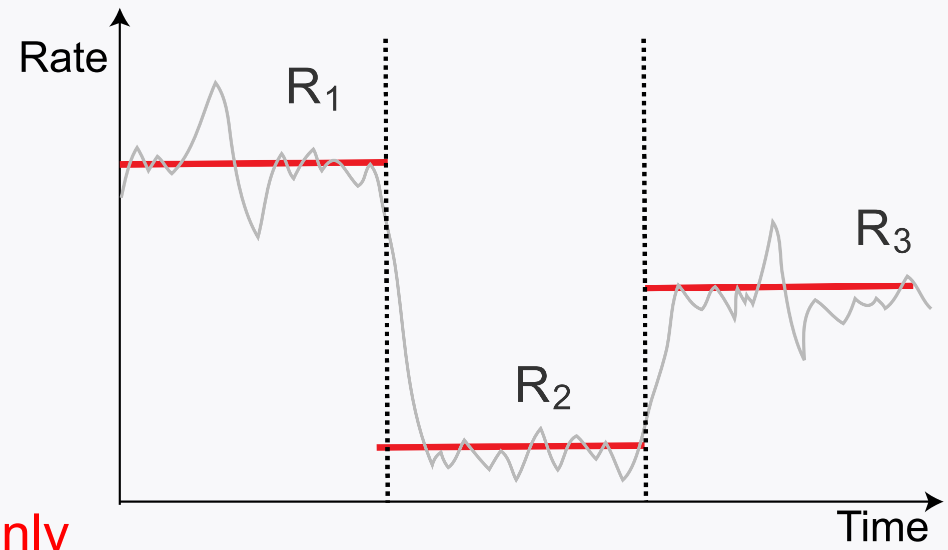
  Rate process: $\{R_k\}$ i.i.d process distributed as *R*

  Disturbances and initial state support: bounded

  Causal knowledge channel: coder and decoder have knowledge of $\{R_i\}_{i=0}^{k}$

  Data rate theorem: $|\lambda|^2 \mathbb{E}\left[2^{-2R}\right] < 1$

  Second moment stability



- Scalar case only

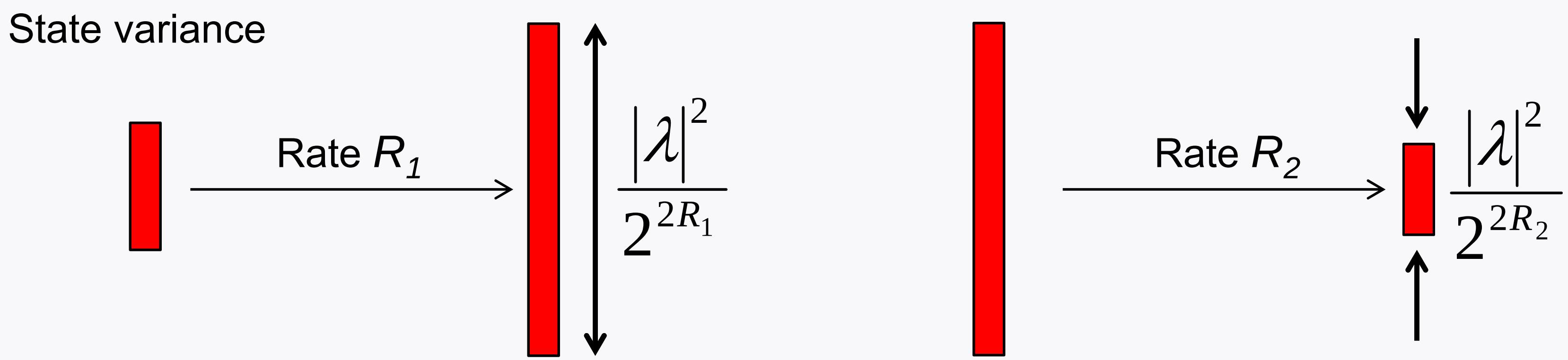
Intuition

- At each time step, the uncertainty volume of the state

$$\uparrow |\lambda|^2 \quad \downarrow 2^{-2R_i}$$

- Keep the *average* of the product less than one for second moment stability

$$|\lambda|^2 \mathbb{E}\left[2^{-2R}\right] < 1$$



Information-theoretic approach

- Minero-F-Dey-Nair (IEEE-TAC 2009)

  Rate process: $\{R_k\}$ i.i.d process distributed as *R*

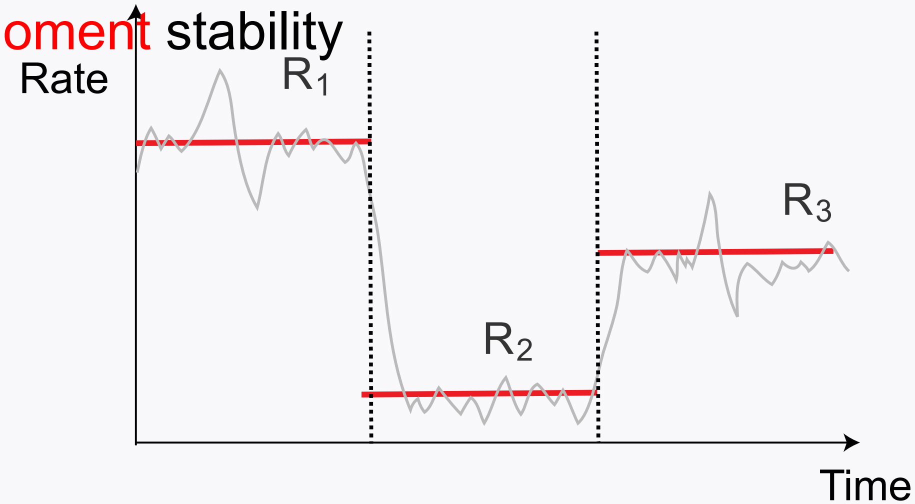
  Disturbances and initial state support: unbounded

  Bounded higher moment (e.g. Gaussian distribution)

  Causal knowledge channel: coder and decoder have knowledge of $\{R_i\}_{i=0}^k$

  Data rate theorem: $|\lambda|^2 \mathbb{E}\left[2^{-2R}\right] < 1$

  Second moment stability



- Vector case, necessary and sufficient conditions almost tight

Proofs

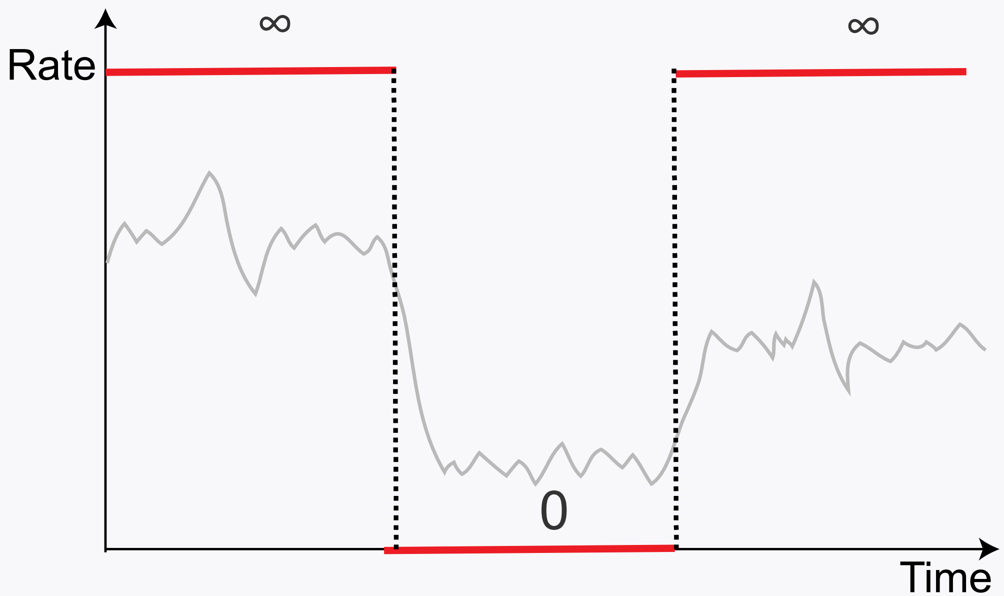
- **Necessity:** Based on entropy power inequality and maximum entropy theorem

- **Sufficiency:** Difficulty is in the unbounded support, uncertainty about the state cannot be confined in any bounded interval, design an adaptive quantizer to avoid saturation, achieve high resolution through successive refinements.

Network-theoretic approach

- A **packet-based** approach (a packet models a real number)

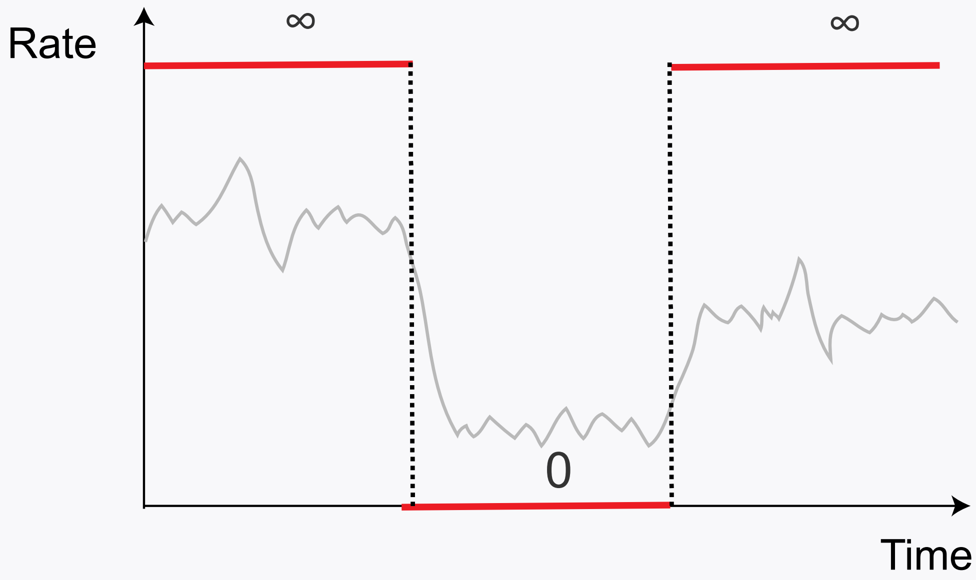
$$R_k = \begin{cases} \infty & \text{w.p. } 1-p \\ 0 & \text{w.p. } p \end{cases}$$



Critical dropout probability

- Sinopoli-Schenato-F-Sastry-Poolla-Jordan (IEEE-TAC 2004)
- Gupta-Murray-Hassibi (System-Control-Letters 2007)
- Elia (System-Control-Letters 2005)

$$p < p_c = \frac{1}{|\lambda|^2}$$



- Generalizes to vector case as:

$$p < p_c = \max_i \frac{1}{|\lambda_i|^2}$$

Critical dropout probability

- Can be viewed as a special case of the information-theoretic approach
- Gaussian disturbance requires unbounded support data rate theorem of Minero, F, Dey, Nair, (2009) to recover the result

$$\mathbb{E}\left[\frac{|\lambda|^2}{2^{2R}}\right] = p\frac{|\lambda|^2}{2^0} + (1-p)\frac{|\lambda|^2}{2^{2r}} < 1$$

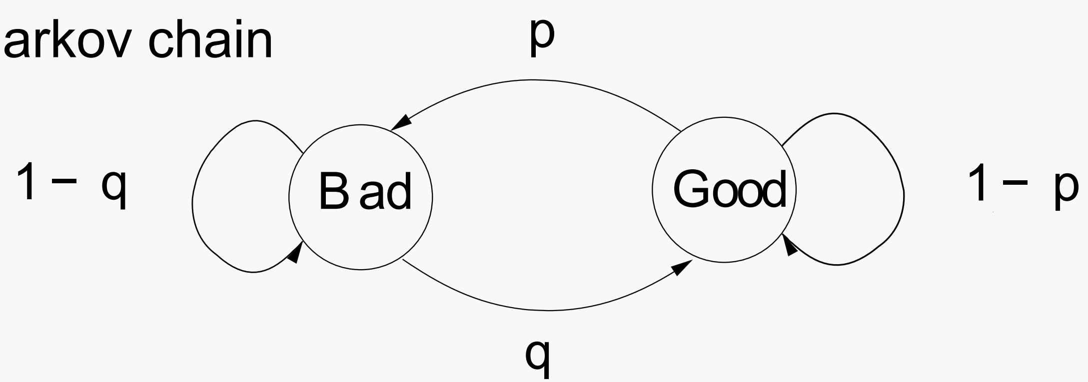
$$\implies p < \frac{1}{|\lambda|^2}, \text{ as } r \to \infty$$

Stabilization over channels with memory

- Gupta-Martins-Baras (IEEE-TAC 2009)

Network theoretic approach

Two-state Markov chain



- Critical “recovery probability”

$$q > q_c = 1 - \frac{1}{|\lambda^2|}$$

Stabilization over channels with memory

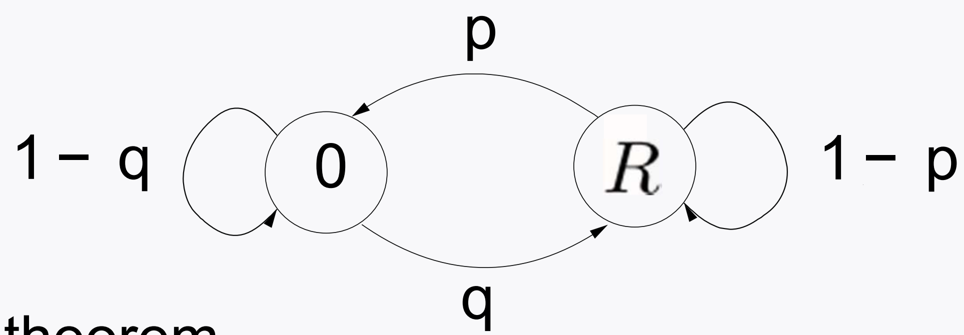
- You-Xie (IEEE-TAC 2010)

  Information-theoretic approach

  Two-state Markov chain, fixed *R* or zero rate

  Disturbances and initial state support: unbounded

  Let T be the excursion time of state *R*



- Data-rate theorem

  $$R > R_c = \frac{1}{2} \log \mathbb{E}[|\lambda|^{2T}]$$

- For $R \to \infty$ recover the critical probability $q > q_c = 1 - \frac{1}{|\lambda^2|}$

Stabilization over channels with memory

- Minero-Coviello-F (IEEE-TAC to appear)

Information-theoretic approach

Disturbances and initial state support: unbounded

Time-varying rate $R_k \in \{r_1, \cdots, r_n\}$

Arbitrary positively recurrent time-invariant Markov chain of *n* states $p_{ij} = P\{R_{k+1} = r_j | R_k = r_i\}$

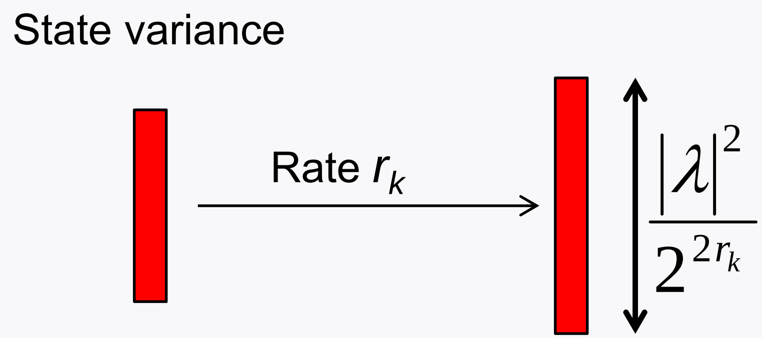
- Obtain a general data rate theorem that recovers all previous results using the theory of Jump Linear Systems

Markov Jump Linear System

- Define an auxiliary dynamical system (MJLS)

$$z_{k+1} = \frac{|\lambda|}{2^{R_k}} z_k + c$$

$$z_0 < \infty, c \geq 0$$



Markov Jump Linear System

- Let H be the $n \times n$ matrix defined by the transition probabilities and the rates

$$h_{ij} = \frac{1}{2^{2r_j}} p_{ji}$$

- Let $\rho(H)$ be the spectral radius of *H*
- The MJLS is mean square stable iff $|\lambda|^2 \rho(H) < 1$
- Relate the stability of MJLS to the stabilizability of our system

Data rate theorem

- Stabilization in mean square sense over Markov time-varying channels is possible if and only if the corresponding MJLS is mean square stable, that is:

$$|\lambda|^2 \rho(H) < 1$$

Previous results as special cases

Minero, Coviello, F (2011)

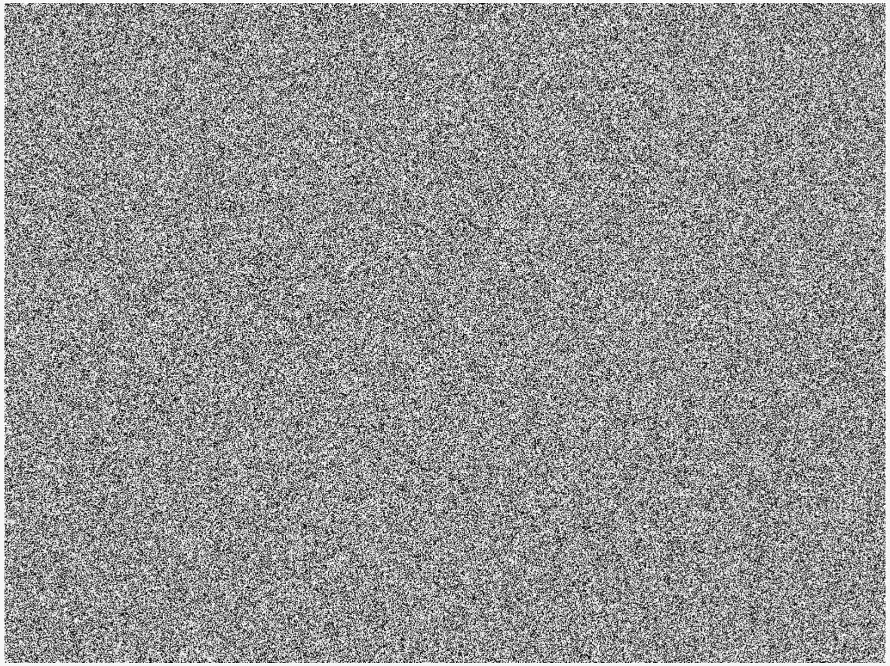
Tatikonda, Mitter (2002)
Nair Evans (2004)
Martins Dahleh Elia (2006)
Minero, F, Dey, Nair (2009)

Gupta Murray Hassibi (2007)
Gupta Martins Baras (2009)

You Xie (2010)

What next

- Is this the end of the journey?



- No! journey is still wide open
- … introducing noisy channels

Insufficiency of Shannon capacity Sahai-Mitter (IEEE-IT 2006)

- Example: i.i.d. erasure channel

$$R_k \sim R = \begin{cases} r & \text{w.p. } 1-p \\ 0 & \text{w.p. } p \end{cases}$$

- Data rate theorem:

$$|\lambda|^2 \mathbb{E}(2^{-2R}) < 1 \qquad \Longrightarrow \qquad |\lambda|^2 (2^{-2r}(1-p) + p) < 1$$

$$\text{as } r \to \infty \quad p < \frac{1}{|\lambda|^2}$$

- Shannon capacity:

$$C = (1-p)r \to \infty$$

Capacity with stronger reliability constraints

- Shannon capacity C soft reliability constraint $P_{err} \to 0$
- Zero-error capacity C_0 hard reliability constraint $P_{err} = 0$
- Anytime capacity C_A medium reliability constraint
  $\mathbb{P}((\hat{M}_{0|k}, \ldots, \hat{M}_{d|k}) \neq (M_0, \ldots, M_d)) = O(2^{-\alpha d}) \quad \text{for all } d \leq k$

$$C_0 \leq C_A \leq C$$

Alternative formulations

- Undisturbed systems
- Tatikonda-Mitter (IEEE-AC 2004)
- Matveev-Savkin (SIAM-JCO 2007)

$C > \log|\lambda|$ a.s. stability

- Disturbed systems (bounded)
- Matveev-Savkin (IJC 2007)

$C_0 > \log|\lambda|$ a.s. stability

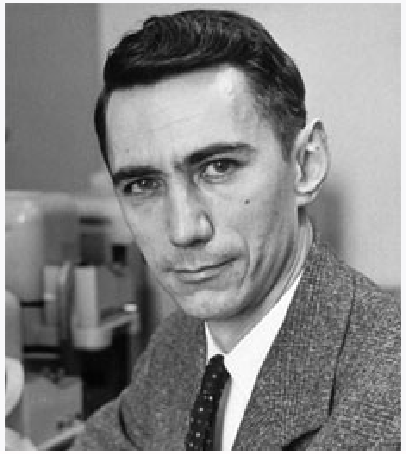
- Sahai-Mitter (IEEE-IT 2006)

$C_A > \log|\lambda|$ moment stability

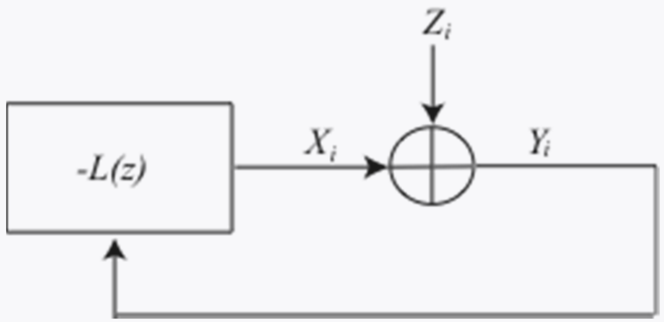
Anytime reliable codes: Shulman (1996), Ostrovsky, Rabani, Schulman (2009), Como, Fagnani, Zampieri (2010), Sukhavasi, Hassibi (2011)

The Bode-Shannon connection

- Connection with the capacity of channels with feedback
- Elia (IEEE-TAC 2004)
- Ardestanizadeh-F (IEEE-TAC 2012)
- Ardestanizadeh-Minero-F (IEEE-IT 2012)



Control over a Gaussian channel Ardestanizadeh, F (2012)



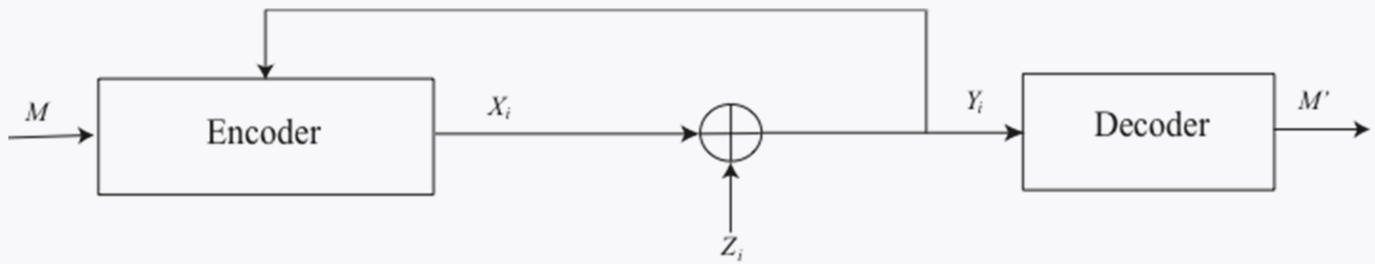
$$U = \sum_{i \in \mathcal{U}} \log |\lambda_i|$$ Instability

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} |T(e^{j\omega})|^2 S_Z(\omega) d\omega \leq P$$ Power constraint

$$T(z) = \frac{L(z)}{1 + L(z)}$$ Complementary sensitivity function

Z_i Stationary (colored) Gaussian noise

Control over a Gaussian channel Ardestanizadeh, F (2012)



$\mathbb{E}(X_i^2) \leq P \;\; \forall i$ Power constraint

C_F Feedback capacity

$$\sup_{\mathcal{L}} U = C_F$$

- The largest instability *U* over all LTI systems that can be stabilized by unit feedback over the stationary Gaussian channel, with power constraint *P* corresponds to the Shannon capacity C_F of the stationary Gaussian channel with feedback [Kim(2010)] with the same power constraint *P*.

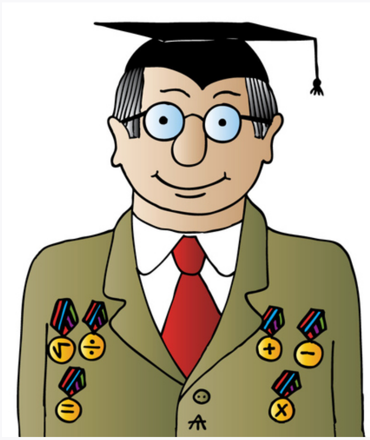
Communication using control

- This duality between control and feedback communication for Gaussian channels can be exploited to design communication schemes using control tools
- MAC, broadcast channels with feedback

- Elia (IEEE-TAC 2004)
- Ardestanizadeh-Minero-F (IEEE-IT 2012)

Conclusion

- Data-rate theorems for stabilization over time-varying rate channels, after a beautiful journey of about a decade, are by now fairly well understood
- The journey (quest) for noisy channels is still going on
- The terrible thing about the quest for truth is that you may find it



- For papers: www.circuit.ucsd.edu/~massimo/papers.html