

Robert Klein, EN-312, 19. September 2012

# VIRTUAL SYSTEM PROTOTYPING.

**RESULTS OF THE MASTER THESIS ROBERT KLEIN  
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PROF. DR. HERBERT PALM, HOCHSCHULE MÜNCHEN.**

**BMW  
GROUP**



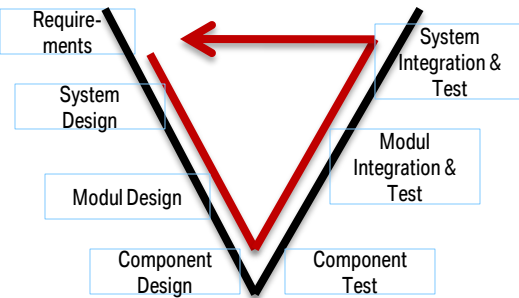
# AGENDA.

- Problem Definition
- Virtual System Prototyping
  - Virtual System Design
  - Virtual System Integration
- Test of Numerical Stability
- Design Evaluation

# PROBLEM DEFINITION.

## As Is

Late system level response



→ The later failures are found, the more expensive they are!

## Problem

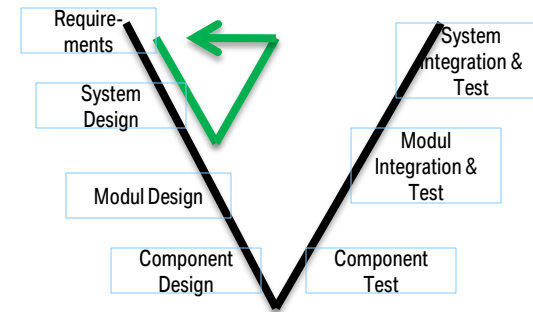
How to achieve an earlier system level response?

## Solution

Virtual System Prototyping

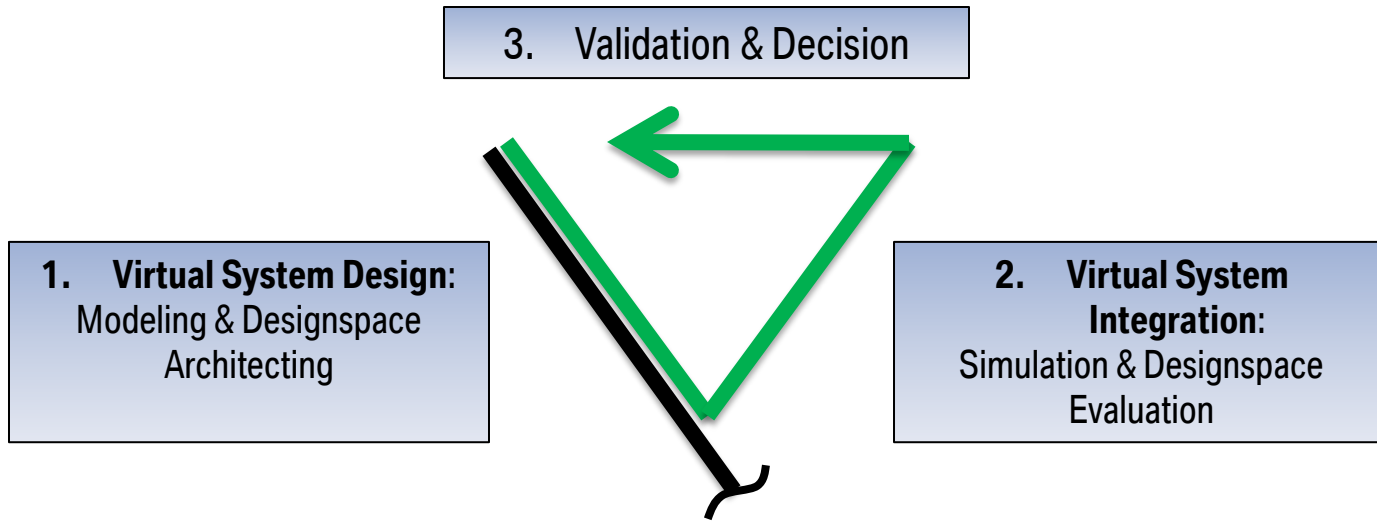
## To Be

Early system level response



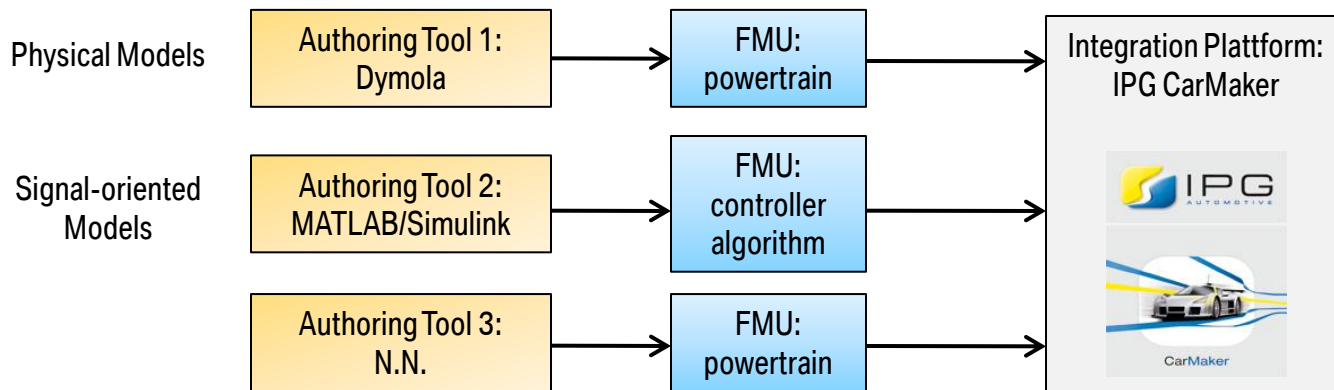
→ Early evaluation of system reduces the risk of missing the „best solution“!

# VIRTUAL SYSTEM PROTOTYPING.



Method

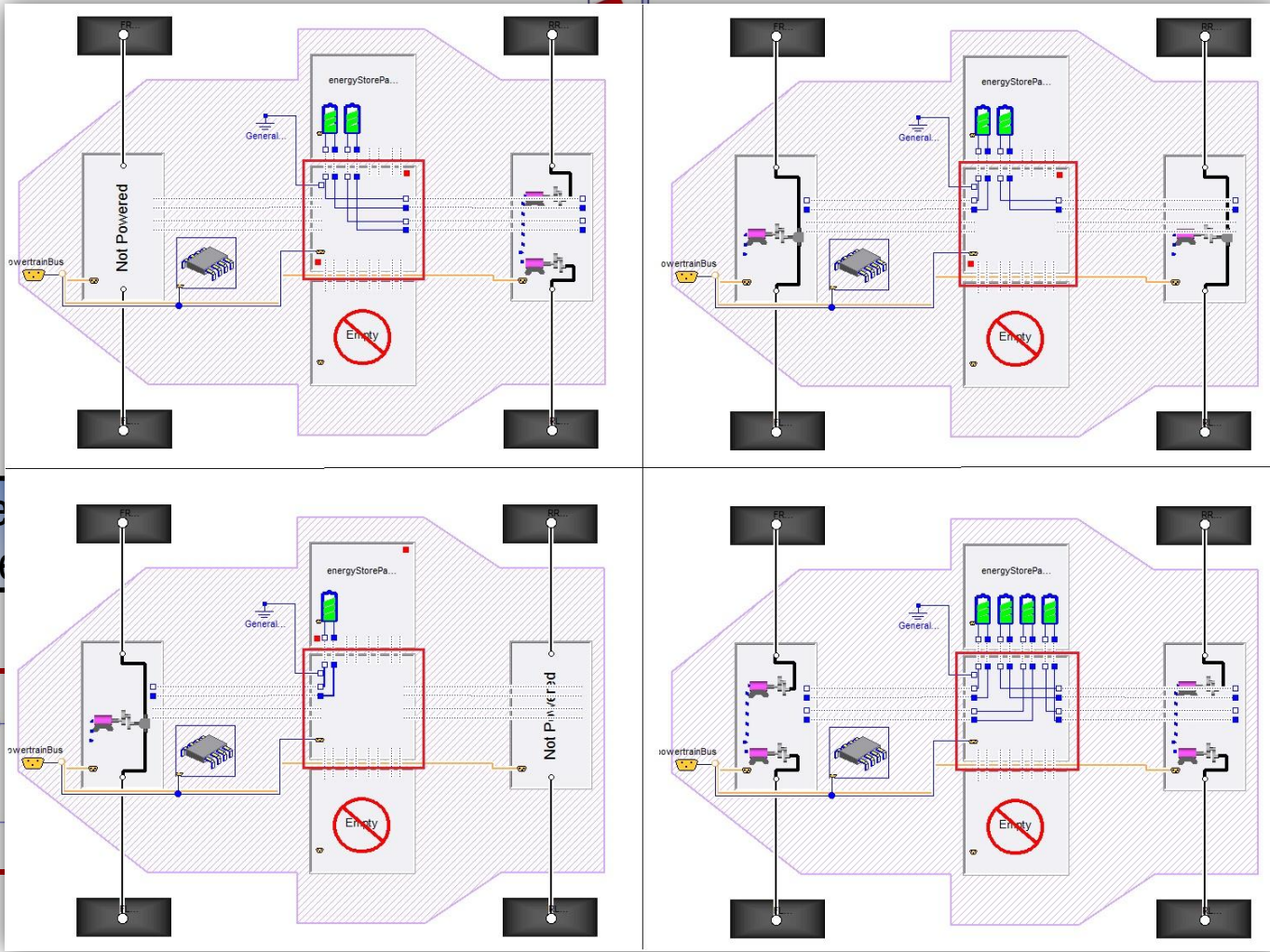
Methodology



Technology

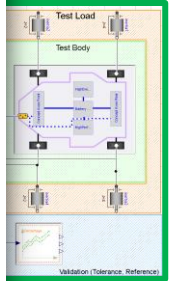
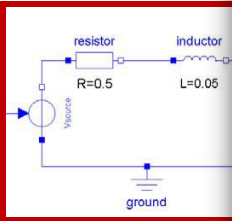
# VIRTUAL SYSTEM DESIGN.

EMAP



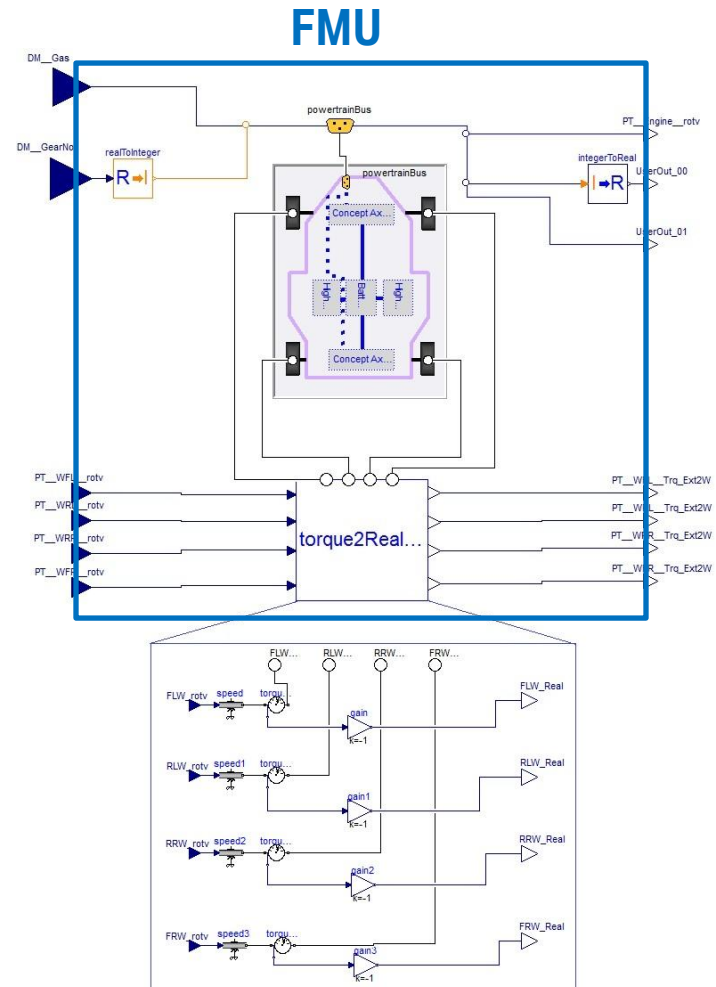
mode  
compon

Update  
lectures



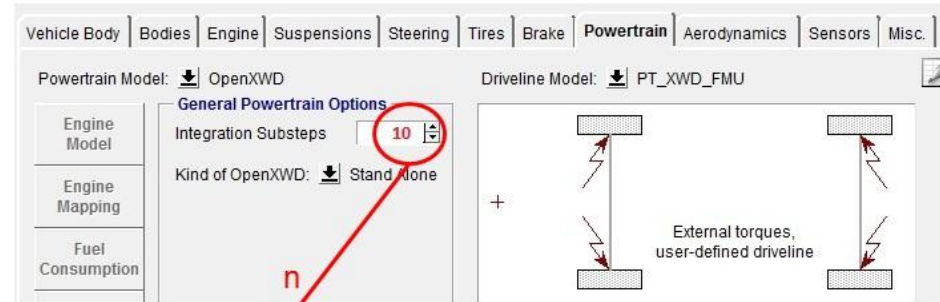
# VIRTUAL SYSTEM INTEGRATION.

1. Definition of FMU with signal-oriented, CarMaker-specific interfaces
2. Converting physical interfaces into signal-oriented interfaces with modelica sensor component
3. Synchronizing axes with modelica speed component



# VIRTUAL SYSTEM INTEGRATION.

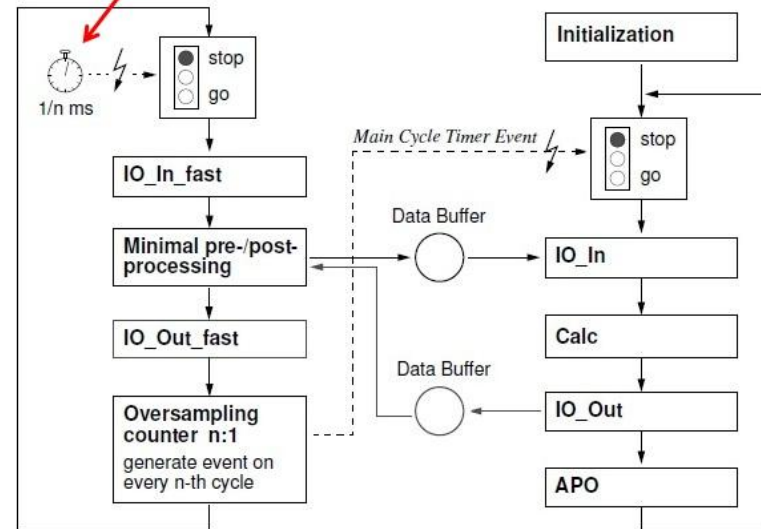
4. Exporting FMU using the Modelon FMI Toolbox
5. Integrating the powertrain model using the OpenXWD framework



**Oversampling Thread**  
Very High Priority

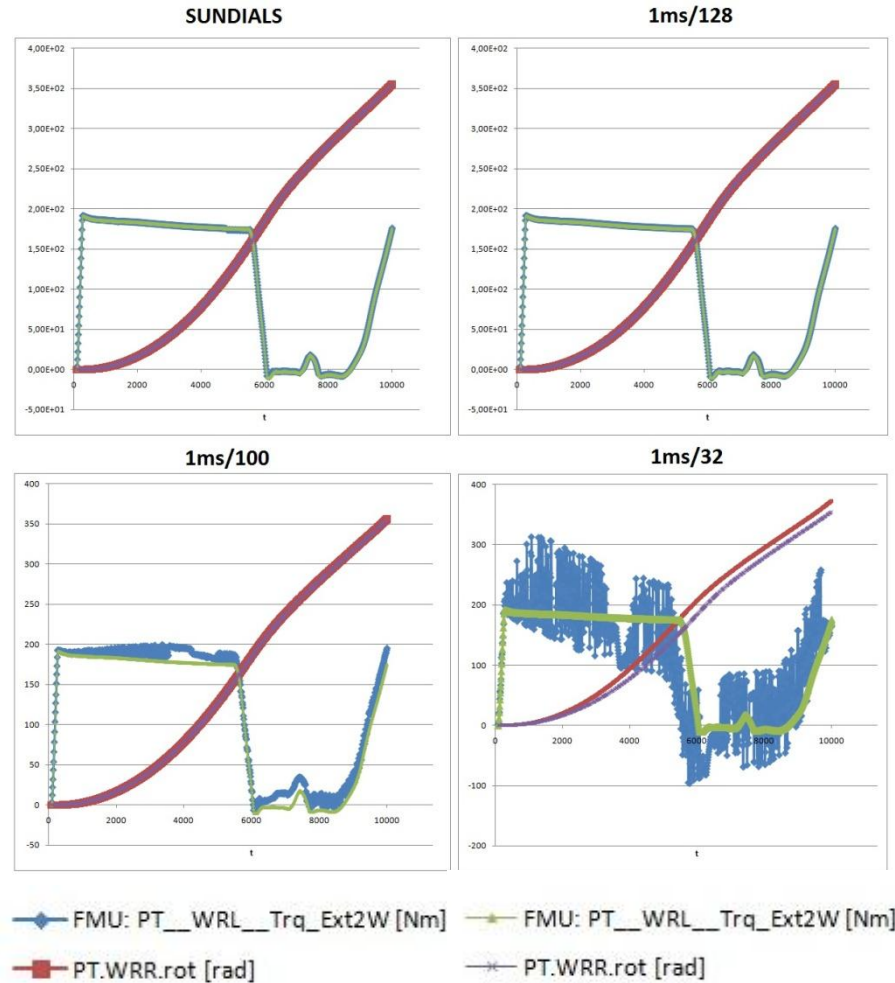
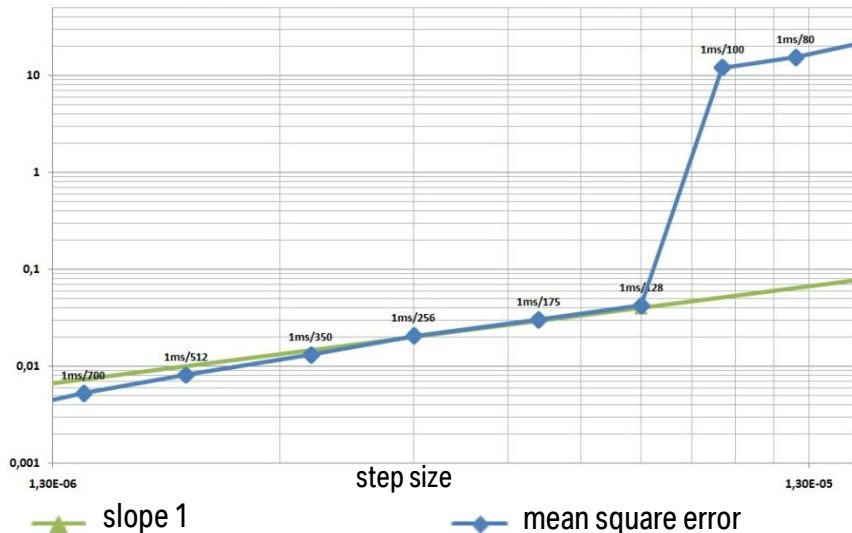
**Main Thread**  
High Priority

→ Use of „Integration Substeps“ with Euler solver possible



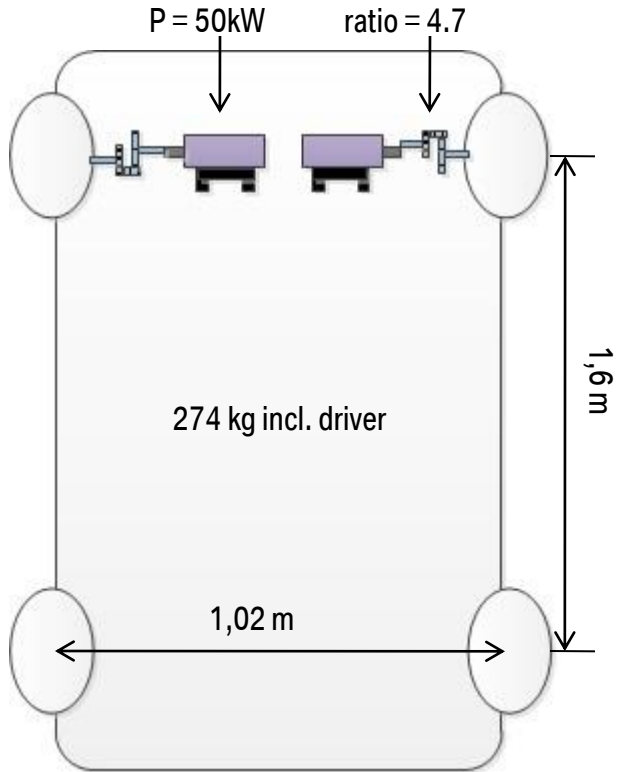
# TEST OF NUMERICAL STABILITY.

- Analysing error with different step sizes
- Mean square error over step size shows euler convergence in stabilized area



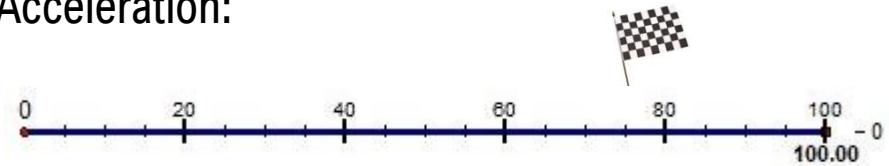


# DESIGN EVALUATION.

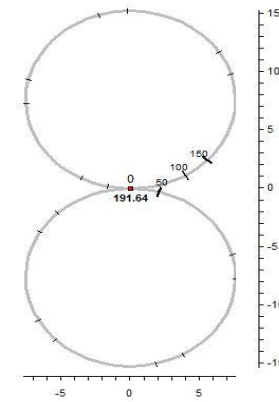


**How does the variation of Engine-Power influences the 3 FSE competitions?**

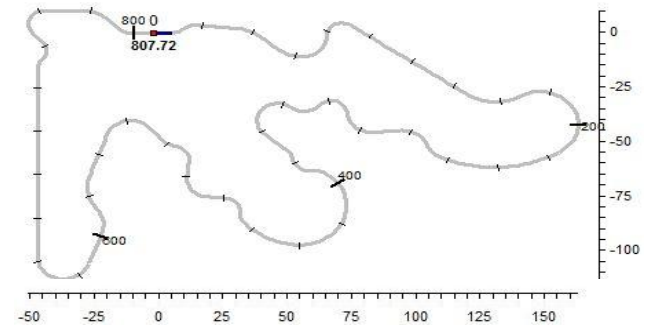
Acceleration:



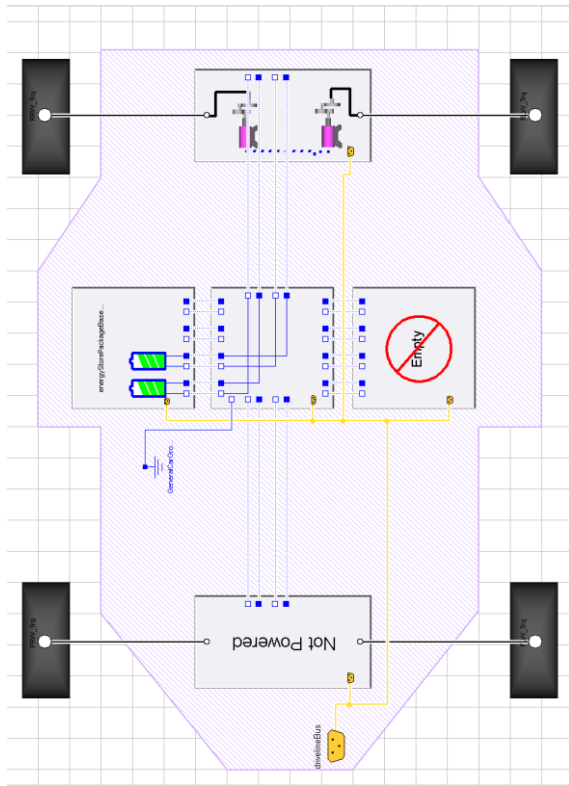
Skidpad:



Endurance:



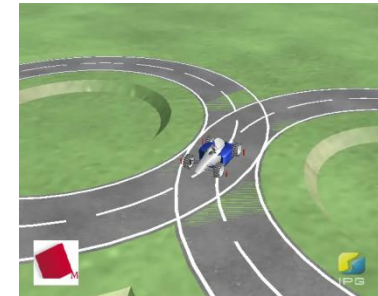
# DESIGN EVALUATION.



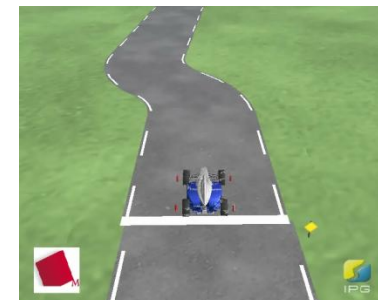
Acceleration:



Skidpad:



Endurance:

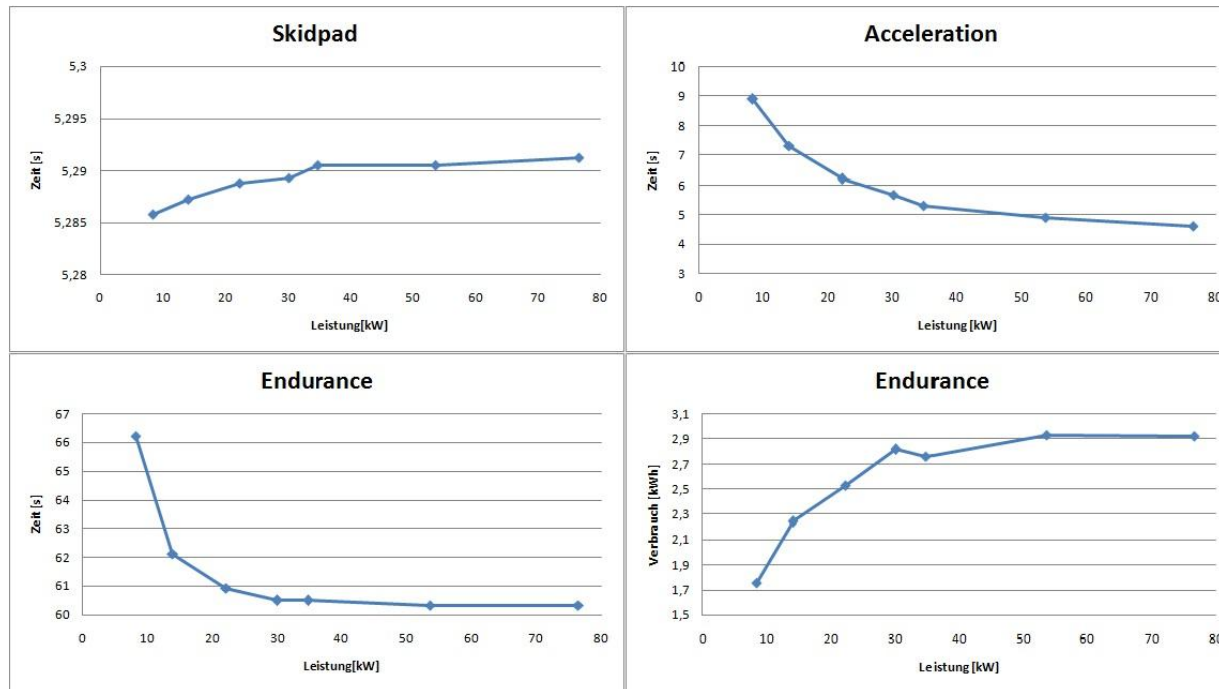


# DESIGN EVALUATION.

	M1	M2	M3	M4	M5	M6	M7
Motor-Speed[rpm]	7600	6000	4000	4320	3300	2900	2300
Motor-Torque[Nm]	90	80	80	64	60	43	32
Motor-Power[kW]	76,5	53,6	34,8	30,1	22,2	14	8,3
Acceleration-Time[s]	4,62	4,91	5,31	5,67	6,2	7,32	8,91
Skidpad-Time[s]	5,29	5,29	5,29	5,29	5,29	5,29	5,29
Endurance-Time[s]	60,3	60,3	60,5	60,5	60,9	62,12	66,2
Endurance-Consumption[kWh] <sup>2</sup>	2,93	2,93	2,76	2,82	2,53	2,24	1,76

M5  
3300  
60  
22,2  
  
6,1  
5,29  
60,9  
2,39

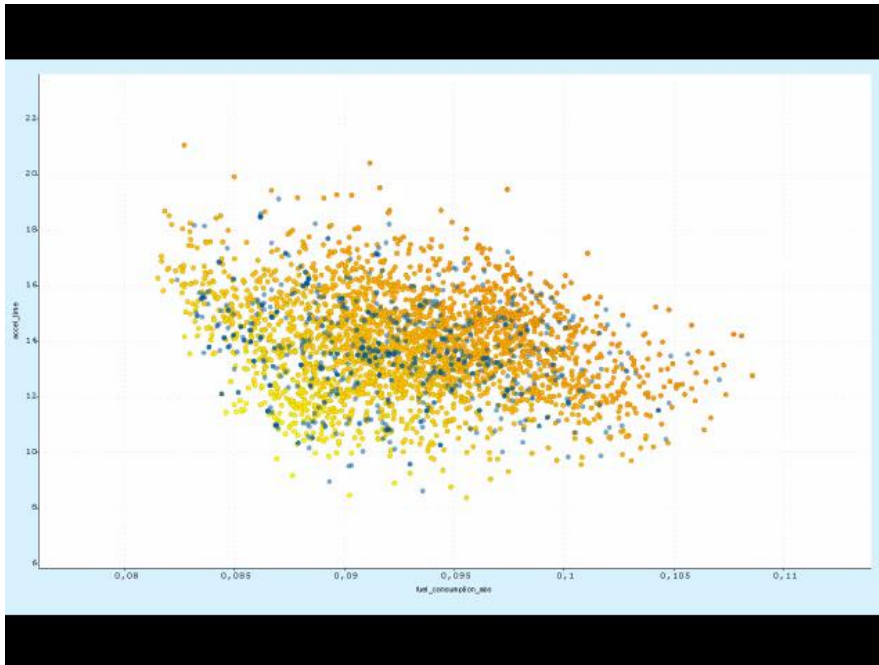
with reduced weight by 20 kg at 274 kg total weight



# PROSPECT.

- Systematic Evaluation with Design of Experiments
- Localize optimized Trade-Offs

Lap Time



Energy consumption

